





WORKSHOP ASI

"L'impegno italiano nel settore dei CubeSat: tecnologie e missioni future" – 2° EDIZIONE

HYPSOS-Earth Observation (HYPSOS PROJECT - Strumento 4D stereoiperspettrale per CubeSat)

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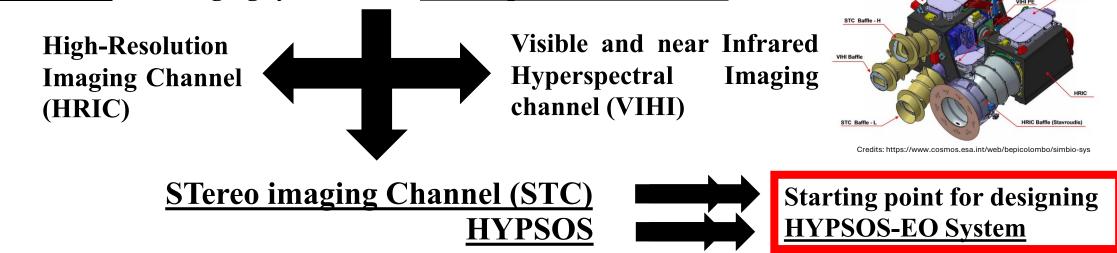




1. INTRODUCTION. HYPSOS-Earth Observation

The <u>Hyperspectral-Stereo Camera for CubeSat (HSSC)</u> of the <u>HYPSOS-EO System</u> is a <u>novel instrument</u> for CubeSat remote sensing able to simultaneously extract 4D information, spatial and spectral, using two channels of a pushbroom stereo camera coupled to a spectrometer. The <u>HYPSOS-EO System represents a</u> precursor in the panorama of Italian Space Activities, being unique in its kind and could be able to generate a great know-how in terms of return on data for the territory. The aim is to obtain an innovative instrument, with a notable scientific/industrial and strategic potential as it is placed in a technologically cutting-edge sector such as the development of optical instrumentation for satellites.

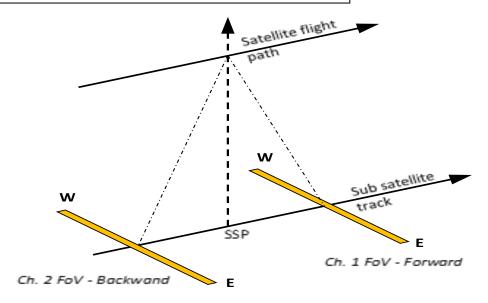
The optical design of HYPSOS-EO is the result of a transfer of knowledge and experience in the realization of <u>SIMBIOSYS</u>, the imaging system of the <u>ESA BepiColombo Mission</u>

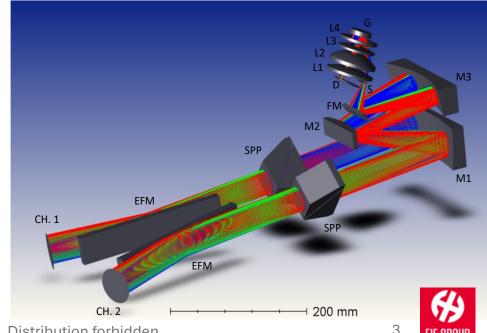




1. INTRODUCTION. From HYPSOS to HYPSOS-Earth Observation

- The possibility of collecting spatial and spectral information with a single observation coupled to stereoscopic capabilities makes HYPSOS (HYPerspectral Stereo Observing System) an innovative new-concept instrument that can be housed on satellites for planetary/lunar remote sensing
- It was decided to develop an apparatus capable of providing a hyperspectral digital terrain model (HDTM) as final product. To achieve this, the design evaluations considered a mission scenario in polar orbit, with a fixed two-channel system (Channel 1 & Channel 2) working in pushbroom mode, where one looks forward and one looks backwards with respect to nadir along the flight direction.

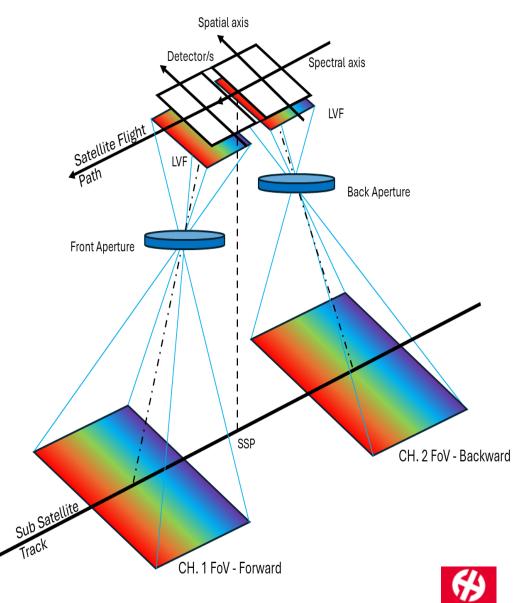






1. INTRODUCTION. HYPSOS-Earth Observation (HYPSOS-EO)

Instrument Environment	LEO-Orbit (400 km)*
System structures	Aluminium panel concept with internal shear
	frame. Turned and milled elements. Metal
	Additive Manufacturing
System size	Payload compartment: ~1U. *Scalable for
	different resolutions.
Thermal Control	Passive cooling of electronics
Subsystem	
Spectral Range	400 - 800 nm (Extendable for IR)
Telescope	Three-Mirror Anastigmat / TMA with two
	symmetric entrance pupils
	Focal Length: ~ 100 mm
	Aperture (Pupil Diameter-D): < 30 mm
	F-number: ~ 10 - 6.7
Spectrometer	Linear Variable Filter (LVF)
	Resolving spectral element (double sampling): <
	10 nm
Spatial Resolution	< 30 m
FoV	~11deg x9deg
	Two Channels folded by ±15° with respect to nadir
www.eie.it	pointing



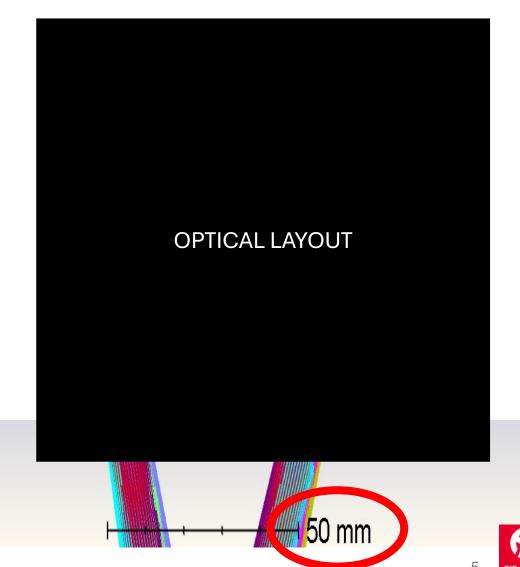
2. HYPSOS-EO. HSSC OPTICAL DESIGN FOR CUBESAT

Telescope

Three-Mirror Anastigmat / TMA with two symmetric entrance pupils

M1	Concave surface	
M2	Convex surface	
M3	Concave oblate surface	
<u>Spectrometer</u>		
LVF	Linear Variable Filter (LVF)	
Sensor: VIS (Possible extension into IR)		

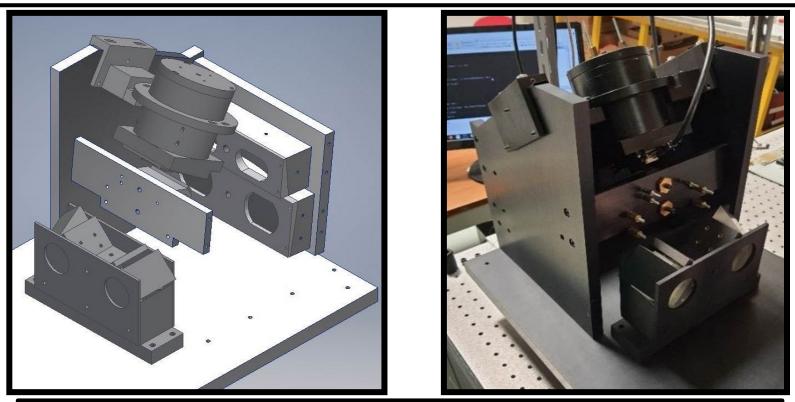
1 or 2 units BI





3. FROM HYPSOS LAB PROTOTYPE TO HYPSOS-EO (CubeSat)

A peculiar feature of HYPSOS is that it has a Three Anastigmatic Mirrors (TMA) telescope configuration whose focal plane corresponds to the spectrometer entrance slit plane. To obtain a single-input slit spectrograph starting from the two separate linear fields of view provided by the pushbroom acquisition mode of the two channels, a 90° field rotation is provided by two 45° inclined Schmidt-Pechan (SPP) prisms, positioned in front of the TMA apertures.



Pubblications:

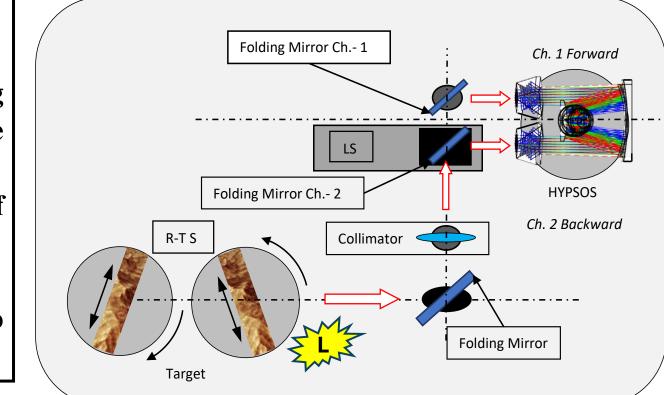
In-lab Characterization of HYPSOS, a Novel Stereo Hyperspectral Observing System: Latest Results
In-lab characterization of HYPSOS, a novel stereo hyperspectral observing system: first results





4. HYPSOS ACQUISITION CONFIGURATION SCHEME (adaptable for HYPSOS-EO)

- > Targets like rocks of different compositions
- > A halogen lamp light source
- A rotational stage capable of reproducing the stereo angle of HYPSOS similar to the flight model
- A translational stage capable of reproducing the push-broom modality
- > A 1010 mm focal length collimator
- A linear stage that selects one of the two acquisition channels.



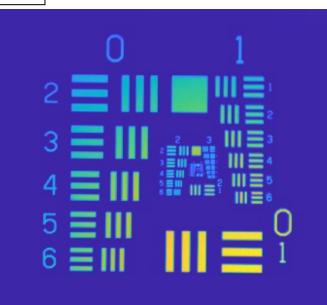
The acquisition system is automatically controlled and synchronizes the speed of the translation stage simulating the pushbroom scan with the acquisition frame rate of the sensor.

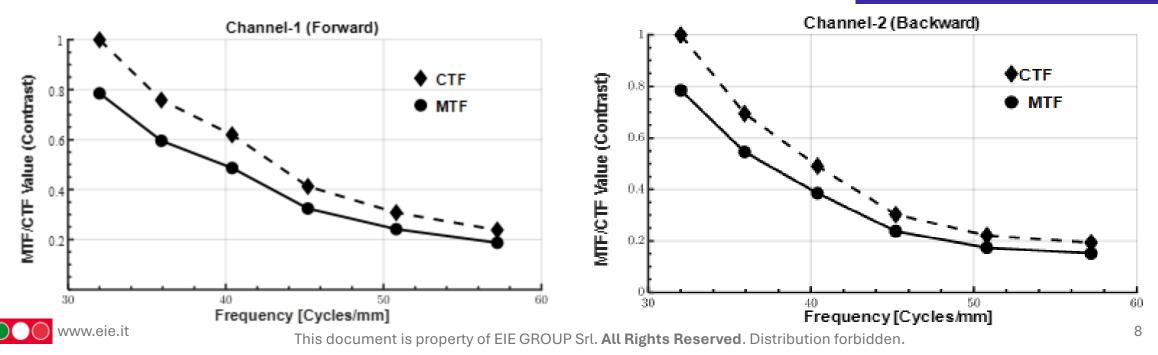




5. HYPSOS TELESCOPE OPTICAL PERFORMANCE

To estimate the telescope performance, the contrast transfer function (CTF) has been measured using a USAF target, and the modulation transfer function (MTF) was then derived

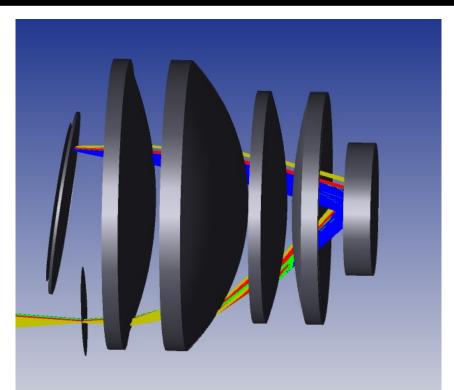


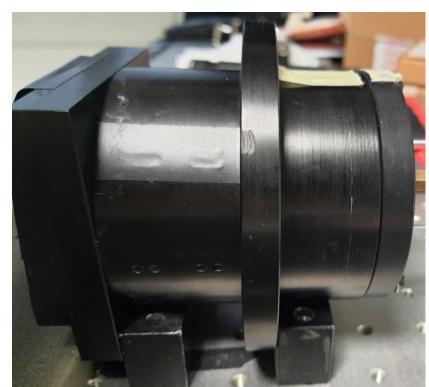


6. HYPSOS SPECTROMETER

Spectrometer Assembling and Integration on HYPSOS

The spectrometer optics have axial symmetry and have been assembled with known mechanical tolerances



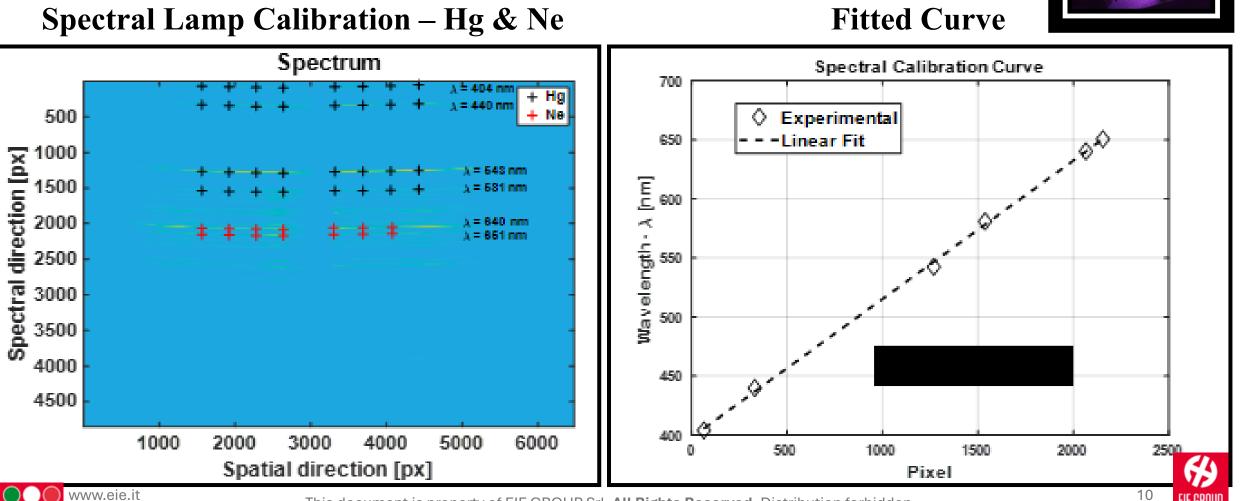


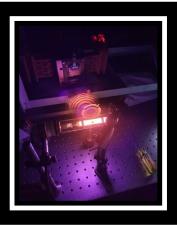




7. HYPSOS SPECTRAL CALIBRATION

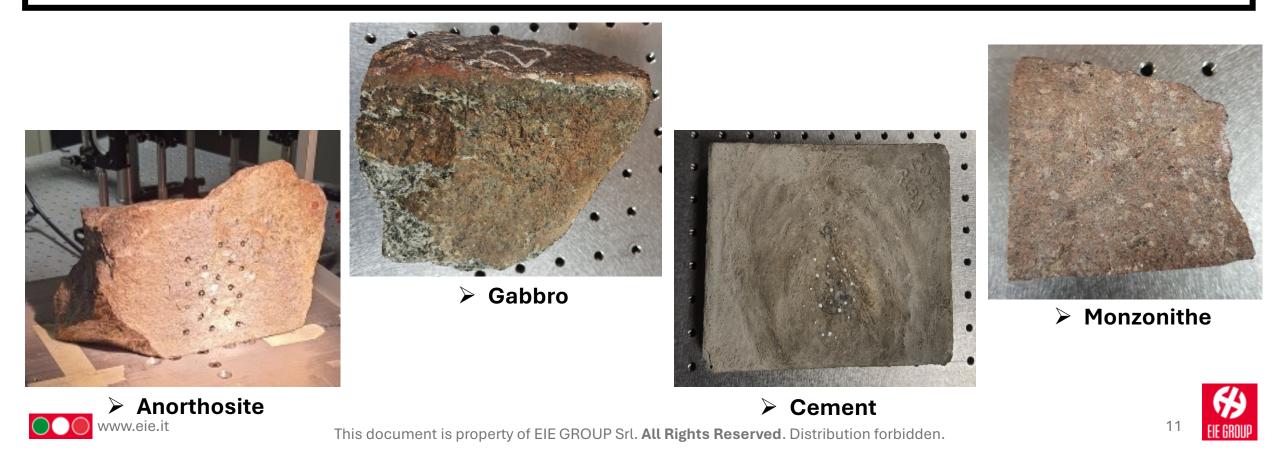
HYPSOS full configuration response





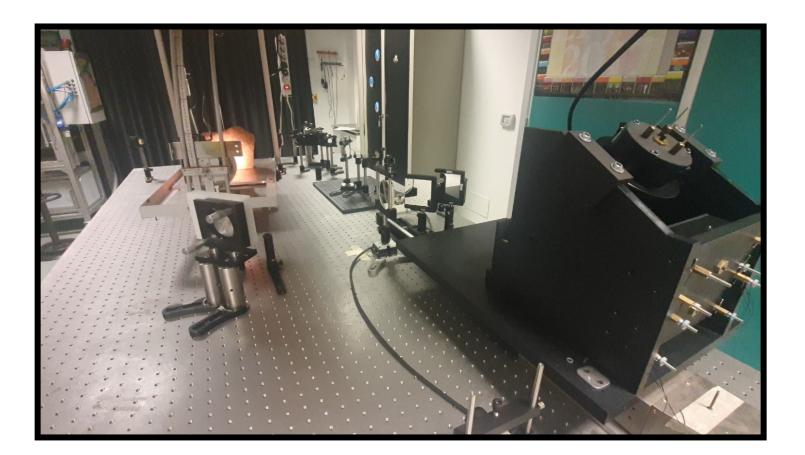
8. OBSERVED TARGETS

*Rocks of different nature and spectral variegations (Anorthosite, Basalt, Cement, ...) are used as 3D targets; their 3D surface has been completely characterized with an accuracy of 20 μm. The halogen lamp illuminates the stones, their diffused light is collected by the collimator and enters HYPSOS apertures for being spatially and spectrally analysed.



9. LABORATORY MEASUREMENTS SETUP

STEREO & PUSHBROOM SETUP SIMULATION

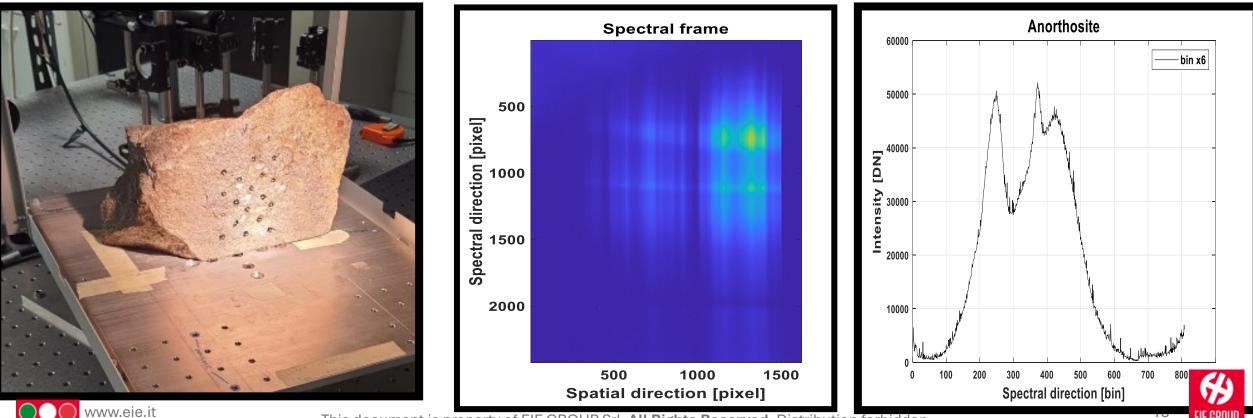






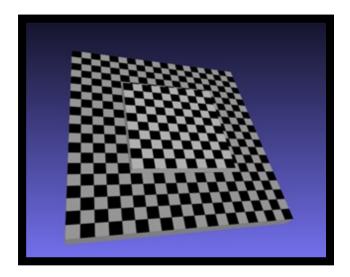
10. SPECTRA ACQUISITION

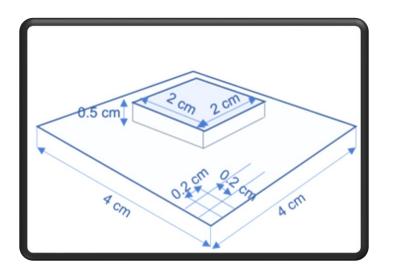
After the integration of the whole instrument, we started to acquire the target spectra simulating the pushbroom acquisition modes



11. HYPSOS PHOTOGRAMMETRIC CALIBRATION

✤ Gauge Reference - This gauge has a large number of three-dimensional reference points, and thanks to them it has been possible to estimate the components of the instrument projection matrix M





* The obtained projection matrix is the compact representation of the internal and external parameters of the camera.

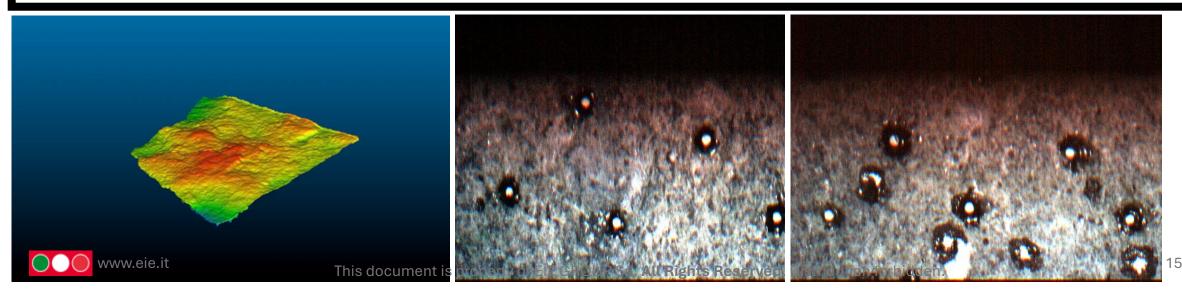




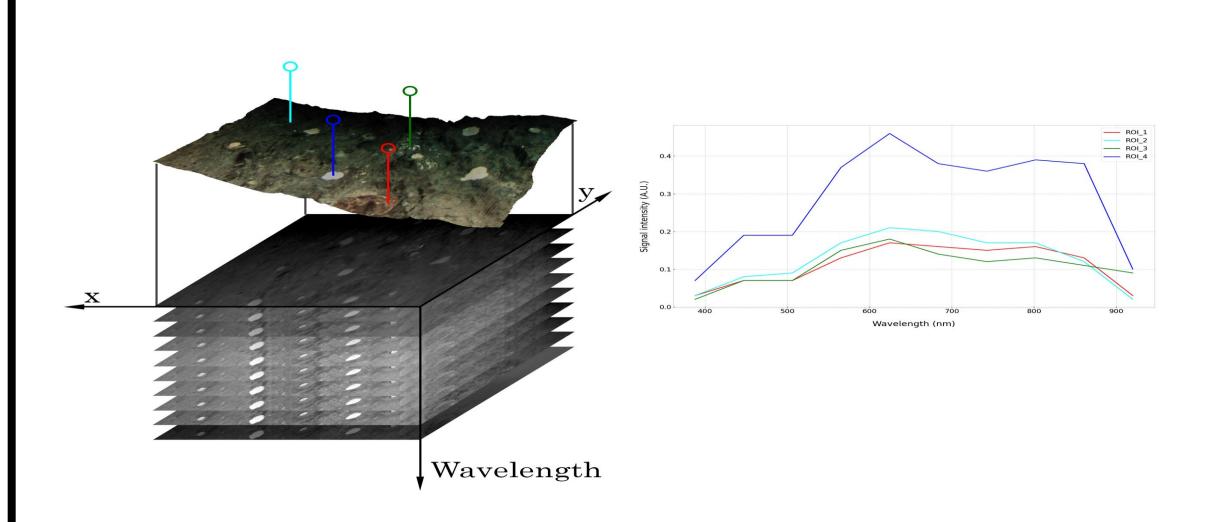
12. HYPSOS PROJECT DATA PROCESS REDUCTION

HYPSOS 3D final product data to validate the system performance

- The extraction of 3D information from the spectral pairs of stereo images acquired with HYPSOS is performed following a specific photogrammetric pipeline
- With the information about the two channels obtained by the calibration process it is possible to analyse the disparity and derive the coordinates 3D in the form of a sparse point cloud or grid DTM
- Comparison methodology will be used: all the targets under measurement by HYPSOS are rock samples whose surface has been previously measured by means of a high precision laser scan system (20 μm resolution) and with known spectral characteristics



13. HYPSOS HYPERSPECTRAL PRODUCTS





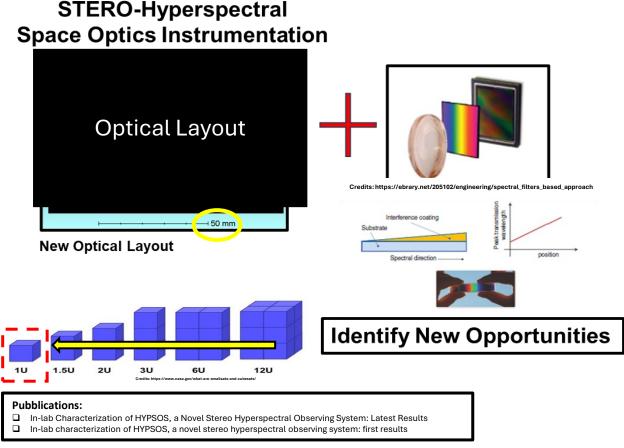




14. FUTURE WORK ON HYPSOS-EO & CONCLUSION

<u>New optimization opportunities have been identified for HYPSOS</u>: → <u>HYPSOS-EO System</u>

- HYPSOS-EO for <u>CUBESAT</u> Application
- Adaptations for Freeform Optics , IR extension, ...
- > AI Algorithms, ...



We have identified some In Orbit Mission to be able to install an IOD HYPSOS-EO or HYPSOS System in the future and test the apparatus.

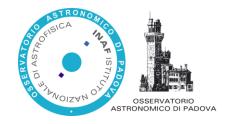
PAYLOAD - 3D CAD MODEL Topological Optimization Concept

Join us...











ACKNOWLEDGEMENTS

<u>Thanks to all the people of the Project Team who</u> <u>participated in the activities</u>

HYPSOS-EO. Opportunity for new agreement...









