

# NanoDynA - 3DOF Testbed for CubeSats Attitude Determination and Control

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# NAUTILUS HERITAGE

#### UNIVERSITÀ DI BOLOGNA



- Orbit determination and radio science experiments for interplanetary missions
- Radio science experiment requirements definition for future deep-space missions experiments (phase A)
- Engineering **software development** and support to **radio science** experiments (phases B/C/D).
- Radio science data pre-processing and calibrations.
- Optical navigation algorithms
- Attitude Determination and Control

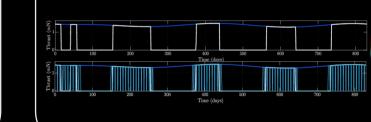


SPIN ALMA MATER STUDIORIM UNIVERSITÀ DI BOLOGNA POLITECNICO DI MILANO

#### POLITECNICO DI MILANO



- Highly non-linear astrodynamics
  - Weak Stability Boundaries
- Autonomous interplanetary GNC
  - **EXTREMA** ERC-funded project
- Optimal Control applications
  - Small Bodies Close Proximity Operations
  - Low-thrust Trajectory Design
- Autonomous Navigation
- Optical Navigation





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NAVIGATION IN SPACE

# NanoDynA CONSORTIUM



**Nautilus Navigation in Space Srl** – Prime Contractor Alfredo Locarini – Project Manager Dario Modenini – Technical Manager



Università di Bologna Andrea Curatolo – System Engineer Daniele Pecorella, Giacomo Curzi, Alessandro Lotti, Project Engineers

INTERDEPARTMENTAL ALMA MATER STUDIORUM **CENTRE FOR INDUSTRIAL** UNIVERSITÀ DI BOLOGNA **AEROSPACE RESEARCH** 

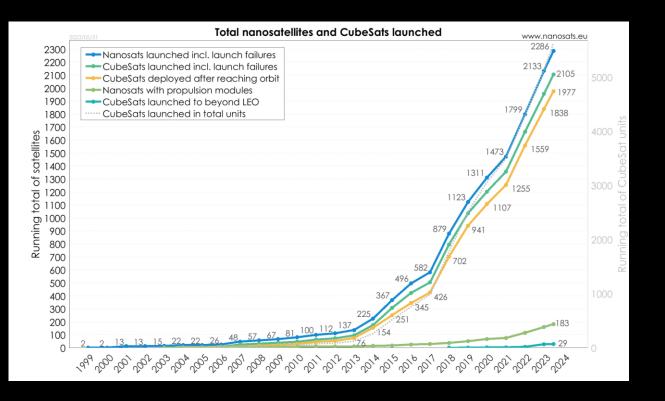


• CCS3 European Space Agency – Funding Institute Andrew Hyslop - Technical Officer

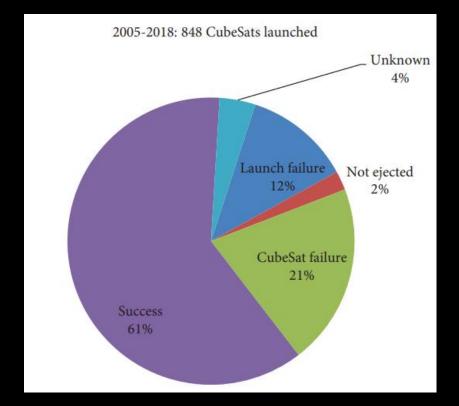
## NanoDynA **CONTEXT**

#### More and more CubeSats launched

#### Still high failure rate



Credit: E. Kulu, \Nanosats database." Available at https://www.nanosats.eu/



Credit: T. Villela, C. Costa, A. Brand~ao, F. Bueno, and R. Leonardi, "Towards the thousandth cubesat: A statistical overview," International Journal of Aerospace Engineering, vol. 2019, pp. 1-13, jan 2019.

# NanoDynA **CONTEXT**

#### "Flatsat" approach

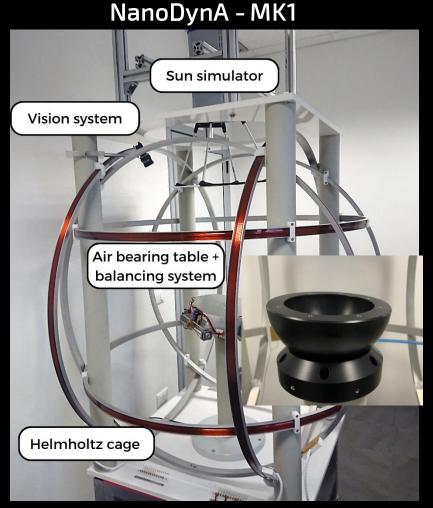


Credit: ESA

#### "Test-as-you-fly" approach



# NanoDynA Heritage: MK1



• Developed at u3S Lab Università di Bologna since 2015

- Based on table-top air bearing, payload capacity  $\approx 5 \text{ kg}$
- COTS triaxial Helmholtz cage for in-orbit magnetic field simulation
- Fixed height pedestal to support the air-bearing table
- Automatic mass balancing system with shifting masses
- Fixed, LED-source Sun simulator
- Monocular ground truth vision system developed in-house
  ≈ 0.3° accuracy

## NanoDynA MK2

- Suitable to test 1U, 3U, 6U and 12U CubeSats with sizes, mass, CoM positions specified by the CubeSat standard
- Standardized mechanical interfaces
- Pedestal with adjustable height for payloads in different orientations
- Mountable battery pack to supply the hosted CubeSat with up to 30 W for 3 hrs at a DC-regulated voltage of 8, 12, 16, 18, or 24 V
- Communication module with CAN and I2C to bi-directional TMTC relaying with ground station
- Simulated Sunlight with different beta angles via movable sun-lamp and Earth's albedo (via Earth albedo lamp)
- Metal Halide Lamp for improved Sunlight spectral matching
- COTS ground-truth system for independent attitude estimation and optionally emulate star tracker accuracy  $\approx 0.1^\circ$
- Compatibility with ISO 8 class clean room/tent

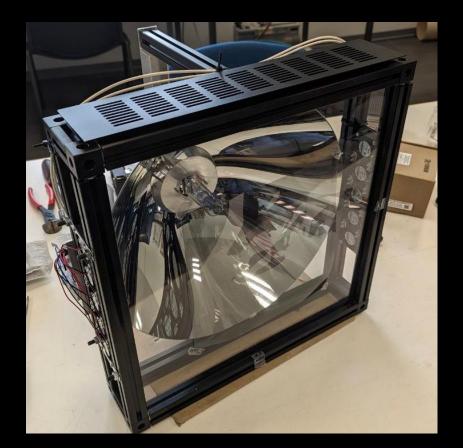


# NanoDynA Magnetic Field Simulator

- COTS Helmholtz cage: Ferronato<sup>®</sup> BH-1300-3-C from Serviciencia - Spain
- Three orthogonal coils ( $D \approx 1300 \text{ mm}$ )
- Arbitrary magnetic field in the range ±10 Gauss
- In-homogeneity below 1% in a sphere of 404 mm in diameter
- Nominal field-to-current ratio 50.5  $\mu$ T/A, ±1%



## NanoDynA Sun Simulator

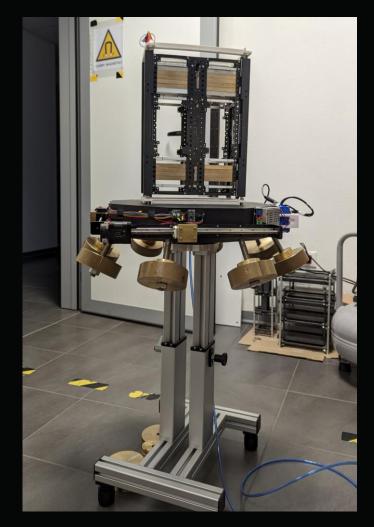


- Metal Halide Bulb for better sunlight spectral matching @ 5600 K
- Highly-accurate electroformed parabolic reflector for collimated light-beam
- Custom mechanical enclosure provides protection in case of catastrophic failure of the bulb
- Includes ten 12V DC fans for heat dissipation
- Frontal polycarbonate panel for UV radiation reduction

#### NanoDynA Tunable beta-angle simulation

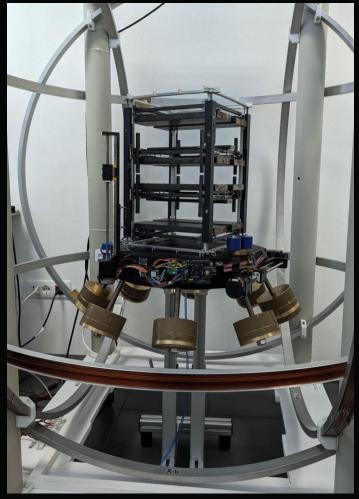


## NanoDynA Standardized Mechanical Interfaces



6U CubeSat Mock-up Mounting (6U Model courtesy of NPC – SpaceMind) Mechanical fixtures act solely on the CubeSat rail profiles interfacing with the deployer

No other contact points to avoid damages



12U CubeSat Mock-up Mounting

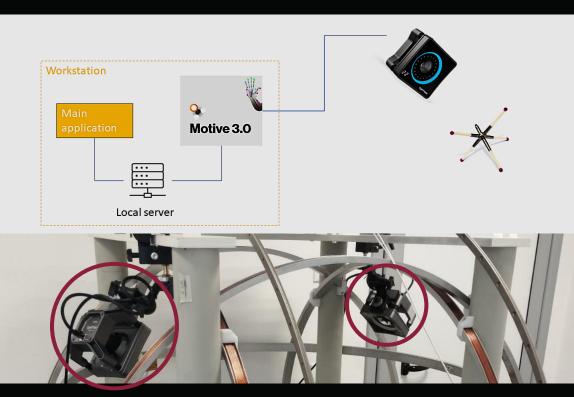
## NanoDynA Mechanical Ground Support Equipment

- Lifter with custom design for positioning 6U and 12U CubeSats within the facility
- Electrically actuated
- Sized to fit within the cage with any orientation of the CubeSat under test
- Cleanroom compatible



## NanoDynA Ground Truth Vision System

- COTS from Optitrack Inc
- High-speed MoCap stereo cameras 2Mpx
- Camera tracks reflective markers
- Pose solution at 200Hz





#### NanoDynA Next Steps

Facility development ends in July 2024

> Delivery and commissioning to ESTEC in September 2024



Planned an upgrade to handle 16U CubeSats in Q4 2024

#### NanoDynA Conclusions

- NanoDynA MK2 is a brand-new facility that implements a "test-as-you-fly" verification approach for the ADCS of CubeSats
- Developed by Nautilus Navigation in Space + Università di Bologna and funded by ESA, its first prototype will be shipped, installed, and commissioned in ESTEC
- The facility is capable of hosting full CubeSat platforms from 1U to 12U in any orientation
- If replicated (and further improved) in Italy, it could serve the ongoing national CubeSats missions, such as those of the Alcor program, as an effective tool for reducing in-flight anomalies thereby contributing to the missions' success



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# UNFOLDING THE DEEP SPACE POTENTIAL



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